

OVERVIEW

D4 is a 360 degrees 2D LiDAR. Based on the principle of Triangulation, it is equipped with related optics, electricity, and algorithm design to achieve high-frequency and high-precision distance measurement. The mechanical structure rotates 360 degrees to continuously output the angle information as well as the point cloud data of the scanning environment while ranging.



TECHNICAL SPECIFICATIONS

PERFORMANCE PARAMETER

| Item | Min | Typical | Max | Unit | Remarks |
|-------------------|-------------------------|--------------------------|---------------------------|------|--|
| Ranging frequency | / | 9000 | / | Hz | / |
| Motor frequency | 5 | 7 | 12 | Hz | Software speed control, default speed = 7Hz |
| Ranging distance | 0.12 | / | 16 | m | Ranging frequency =4KHz (to be customized), 80% Reflectivity |
| | 0.26 | / | 16 | m | Ranging frequency =8KHz (to be customized), 80% Reflectivity |
| | 0.28 | / | 16 | m | Ranging frequency =9KHz, 80% Reflectivity |
| Field of view | / | 0-360 | / | Deg | / |
| Systematic error | / | 2 | / | cm | Range ≤ 1m |
| Relative error | / | 2.0% | / | / | 1m < range ≤ 8m |
| Tilt angle | 0.25 | 1 | 1.75 | Deg | / |
| Angle resolution | 0.2 (Frequency @5Hz) | 0.28 (Frequency @7Hz) | 0.48 (Frequency @12Hz) | Deg | When motor frequency =7Hz, and the ranging Frequency =9000Hz |

ELECTRICAL PARAMETER

| Item | Min | Typical | Max | Unit | Remarks |
|------------------|------|---------|-----|------|--|
| Supply voltage | 4.8 | 5.0 | 5.2 | V | Excessive voltage might damage the Lidar while low affect normal performance |
| Startup current | 1000 | / | / | mA | The driving capability that the power supply for the lidar needs to meet |
| Sleeping current | / | / | 50 | mA | System sleep, motor stops |
| Working current | / | 350 | 500 | mA | System work, motor speed=7Hz |


INTERFACE DEFINITION

| Pin | Type | Description | Defaults | Range | Remarks |
|-----|--------------|---------------------------|----------|-----------|-----------------------------------|
| VCC | Power supply | Positive | 5V | 4.8V-5.2V | / |
| Tx | Output | System serial port output | / | / | Data stream: LiDAR→Peripherals |
| Rx | Input | System serial port Input | / | / | Data stream: Peripherals→LiDAR |
| GND | Power supply | Negative | 0V | 0V | / |
| NC | Reserve | Reserved pin | / | / | / |

SERIAL PORT SPECIFICATION

| Item | Min | Typical | Max | Unit | Remarks |
|-------------------|-----|---------|-----|------|---------------------------------------|
| Baud rate | / | 230400 | / | bps | 8-bit data bit, 1 stop bit, no parity |
| High signal level | 2.4 | 3.3 | 3.5 | V | / |
| Low signal level | 0 | 0.3 | 0.6 | V | / |

LASER OPTICAL PARAMETERS

| Item | Min | Typical | Max | Unit | Remarks |
|------------------|--|---------|-----|------|---------------|
| Laser wavelength | 775 | 792 | 800 | nm | Infrared band |
| Laser power | / | 3.5 | 6 | mw | Average power |
| FDA |  Class I IEC60825-1 | | | | |

OTHERS

| Item | Min | Typical | Max | Unit | Remarks |
|-----------------------|-----|---------|------|------|---|
| Operating temperature | 0 | 20 | 50 | °C | Long-term working in a high temperature environment will reduce the life span |
| Storage temperature | -10 | / | 60 | °C | / |
| Lighting environment | 0 | 550 | 2000 | Lux | For reference only |
| weight | / | 214 | / | g | / |